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### Multimodal Location Based Services Semantic 3D City Data as Virtual and Augmented Reality



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# Collaboration







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# ULPGC

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• Urban and energy-related data models

Tools: The Glob3 Mobile framework

• Virtual Globe View

• Project Goals

- Virtual Reality Mono
- Virtual Reality Stereo
- Augmented Reality
- Use case: Visualising solar irradiation
- Conclusions

# Outline



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# Project Goals

- Prototype an interactive and mobile system for exploring:
  - Semantic building / urban representational models (e.g. CityGML)
  - Energy related data sets.
- Explore the possibilities of multi-LoD maps, Virtual Reality and Augmented Reality for the visualisation of 3D urban models and temporal data-series.
- Create a iOS app, that serves as demonstration of the service.











### Urban and energy-related data models

- **CityGML**: Information model for urban objects representation.
- Extension of GML (from OGC)
- Classes, hierarchies, aggregations, relations, and properties.
- Used on 3D virtual cities, analysis, simulation...
- Extendable via Application Domain Extensions (ADE)
- Buildings represented in different levels of detail.





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### Urban and energy-related data models

Karlsruhe Model: CityGML LoD 2

**CityStats, Heat D./ L.**:Energy-related data per building

SolarB: Temporal data-series representing energy simulations



Based on Nichersu and Simons (2014) and extended by Wieland et al. (2015), Saed and Wendel (2015)





### Urban and energy-related data models

- Karlsruhe model
  - +30.000 buildings [LoD2] (from a total set of 80.000).
  - +230.000 surfaces [Grounds, Walls and Rooftops]
  - Building parameters:
    - Heat demand, Volume, GHG Emissions, solar gains, 50 demographic variables...
  - High resolution textured models of emblematic buildings and monuments.





# Glob3 Mobile

- Open-source framework for Map & Virtual Globe Applications.
- Native implementations for iOS, Android and Web.
- Developed by CTIM (ULPGC) and IGO Software.
- Available: <u>https://github.com/glob3mobile/g3m</u>
- Automatic Multiplatform Porting







### G3m Features

#### Many kinds of scenario







### G3m Features 2D/2.5D/3D Interactive Symbology









## CityGML to 3D

- OpenGL / WebGL only understand triangles!
- The data received via CityGML needs to be translated into a triangulated mesh model to be displayed.
  - Model storage can be local or on a remote server.
    - Karlsruhe model  $\sim$  = 400 MB.
  - Fetching, parsing and tessellation are executed on parallel threads.





# CityGML to 3D: Parsing

• SAX Parsing of the CityGML documents:







# CityGML to 3D: Tessellation

- Creating a single triangular mesh of buildings.
  - For a high number of models, batched drawing is essential [x49]





- Visibility test, eliminating shared walls.
  - Proximity based limiting the O(n!) complexity.
- EPSG:4326 to Cartesian World Coordinates
  - Addition of DEM displacement
- Ear Clipping Algorithm for wall tessellation
  - Computationally expensive algorithm [O(n<sup>2</sup>)]
    - 91% of tessellated surfaces are 4 edged.







http://www.sunshine2k.de/coding/java/Polygon/Kong/ Kong.html

### Culpge Multimodal App: Virtual Globe

- Classic GIS 3D map approach.
- Multitouch navigation.



- Buildings are selectable showing their associated data.
- OpenStreet Map as base layer. [Mapnik]





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### ULPGC Multimodal App: Virtual Globe







- Sensors output of iOS, Android and Javascript.
- Control the UI rotations.
- Device location given by GPS.



Multiplatform device-attitude representations



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ULPGC Multimodal App: Virtual Reality







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# Multimodal App: VR Stereo

- Stereo rendering of the scene
  - Low-level OpenGL coding from scratch.
  - Stereo parallel projection.
  - Using a 1:1 scale for the interaxial.
  - Stereo frustum culling to improve performance.







## Multimodal App: VR Stereo

• Use of Cardboard-like VR headsets.





# Multimodal App: Augmented Reality

- Device Attitude Tracking + Real Image Merging
- Phone's camera has to be mathematically represented.
  - Intrinsic parameters obtained with OpenCV.

$$\begin{bmatrix} u \\ v \\ 1 \end{bmatrix} = \begin{bmatrix} f_x & 0 & c_x \\ 0 & f_y & c_y \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} r_{11} & r_{12} & r_{13} & t_1 \\ r_{21} & r_{22} & r_{23} & t_2 \\ r_{31} & r_{32} & r_{33} & t_3 \end{bmatrix} \begin{bmatrix} X \\ Y \\ Z \\ 1 \end{bmatrix}$$









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## Use case:



# SolarB – Solar irradiance model

- Numerical simulation of the amount of sunlight captured by the building surfaces.
  - Based on Šúri, M. and Hofierka, J. (2004)
- Final result: Temporal data series of Solar radiation per time interval for surfaces and buildings [kWh]
  - Surfaces represented as point sets with a resolution of  $1 \text{ p/m}^2$ .



a) Building part classification

b) Point grid generation



c) Shadowing analysis

d) Aggregation of results



### Use case:



# SolarB – Solar irradiance model

- Example: The EIFER offices in Karlsruhe (7 stories)
  - 14 surfaces [3071 points]
  - 1 year of solar irradiation data [8760 timestamps]









## Conclusions

- The prototype demonstrates feasible to apply mobile computer graphics technologies to the study of massive urban datasets.
- The app is able to directly retrieve semantic building data from energy simulations/models in a standardised way (OGC, CityGML structure).
- VR and AR are useful techniques for field experts on energy research and infrastructure maintenance.
- For medium sized cities, multi-level-of-detail is not necessary.
- GPS & Compass accuracy for VR and specially for AR is still unreliable on many urban situations.
  - Alternative positioning techniques could achieve better results.



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### Thanks for your attention



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